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Patent Application of
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for

TITLE: A SYSTEM AND METHOD FOR REMOTELY CONTROLLING AND MONITORING A
PLURALITY OF COMPUTER SYSTEMS

TITLE OF INVENTION

A system and method for remotely controlling and monitoring a plurality
of computer systems.

CROSS-REFERENCE TO RELATED APPLICATIONS

Not applicable.

STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH OR DEVELOPMENT

Not applicable.

REFERENCE TO MICROFICHE APPENDIX

Not applicable.

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BACKGROUND OF THE INVENTION - FIELD OF INVENTION

This invention relates to the control and monitoring of computers, specifically to an improved Keyboard-Video-Mouse switch fully integrated with a video display, character input device, and pointing device.

BACKGROUND OF THE INVENTION - DISCUSSION OF PRIOR ART

Many computers capable of performing general purpose and specialized tasks require a computer room with raised flooring and air conditioning. Because computer room space is quite expensive, such computers must be mounted in a rack. Having a separate video display, character input device, and pointing device for each computer is impractical and wastes valuable computer room space. Keyboard-Video-Mouse (KVM) switches were developed which allows a single video display, character input device, and pointing device to communicate with one or more rack-mounted computers. However, requiring a separate video display, a separate character input device, a separate pointing device, and a separate KVM switch has the disadvantages of:

- (a) consuming valuable rack space
- (b) requiring a separate connector for video display, character input, and pointing data and signals on the KVM switch
- (c) likelihood of malfunction due to a loose connection or failure of the aforementioned connectors and cables

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Objects and Advantages

- (a) To provide a compact control and monitoring system which minimizes the amount of rack space consumed by the following separate elements: KVM switch, video display, character input device, and pointing device;
- (b) To provide a compact control and monitoring system which accepts data for video display and transmits data for character input and pointing to a computer but requires a single connector at the KVM switch;
- (c) To provide a compact control and monitoring system which reduces the likelihood of a malfunction due to a loose connection or cable failure by reducing the number of cables and connections that must be made;
- (d) To provide a compact control and monitoring system which extends out of a rack as a single unit;

- (a) To provide a control and monitoring system which allows upgrades, downloading or uploading of code, testing, and configuration from a remote location;
- (b) To provide a control and monitoring system which can communicate with other control and monitoring systems;
- (c) To provide a plurality of interconnected control and monitoring systems which appear to be a single control and monitoring system to a human user;

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- (d) To provide a control and monitoring system which has the ability to switch off power to the video display after a period of time has elapsed, where said period of time has been specified by a human user;
 - (e) To provide a control and monitoring system which utilizes a plurality of processing units, thereby reducing the likelihood of losing data from one of the computers connected to the compact control and monitoring system;
 - (f) To provide a control and monitoring system where a video display, a character input device, and a pointing device are protected from dust and impact from objects when the control and monitoring system is stored in a rack;
 - (g) To provide a control and monitoring system where no special software or hardware is required on the computer being monitored or controlled.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWING

Fig. 1 shows a rear view of the main unit.

Fig. 2 shows front view of the main unit.

Fig. 3 shows a rear view as installed in a rack.

Fig. 4 shows a front view as installed in a rack.

Fig. 5 shows a cable used to connect a computer system to the control and monitoring system.

Fig. 6 shows the connectors used on the cable used to connect a computer system to the control and monitoring system.

Figs. 7 and 8 show a block diagram of the control and monitoring system.

Fig. 9 shows a cable used to daisy chain multiple control and monitoring systems together.

Fig. 10 shows the connectors used on the cable in Fig. 9.

Fig. 11 shows a schematic view of a terminator used on the open end of the last cable used in a daisy chain of multiple control and monitoring systems.

Fig. 12A shows a rear view of the terminator in Fig. 11.

Fig. 12B shows a front view of the terminator in Fig. 11.

Reference Numerals In Drawings

8	Housing
10	External Video Out - fifteen position D-sub
12	Communications Port
14	External Keyboard Port - Mini-DIN
16	External Mouse Port - Mini-DIN
20	Keyboard-Video-Mouse Port 1 - fifteen position D-sub
22	Keyboard-Video-Mouse Port 2 - fifteen position D-sub
24	Keyboard-Video-Mouse Port 3 - fifteen position D-sub
26	Keyboard-Video-Mouse Port 4 - fifteen position D-sub
28	Keyboard-Video-Mouse Port 5 - fifteen position D-sub
30	Keyboard-Video-Mouse Port 6 - fifteen position D-sub
32	Keyboard-Video-Mouse Port 7 - fifteen position D-sub
34	Keyboard-Video-Mouse Port 8 - fifteen position D-sub

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124	KVM Connector Position 4 - Keyboard Power
125	KVM Connector Position 5 - Keyboard Clock
126	KVM Connector Position 6 - Video Ground
127	KVM Connector Position 7 - Video Ground
128	KVM Connector Position 8 - Video Ground
129	KVM Connector Position 9 - Mouse Power
130	KVM Connector Position 10 - Keyboard Data
131	KVM Connector Position 11 - Mouse Clock
132	KVM Connector Position 12 - Mouse Data
133	KVM Connector Position 13 - Horizontal Sync
134	KVM Connector Position 14 - Vertical Sync
135	KVM Connector Position 15 - Keyboard and Mouse Ground
141	Video Connector Position 1 - Red Video
142	Video Connector Position 2 - Green Video
143	Video Connector Position 3 - Blue Video
144	Video Connector Position 4 - ID BIT 2
145	Video Connector Position 5 - DDC Signal Return
146	Video Connector Position 6 - Red Video Signal Return
147	Video Connector Position 7 - Green Video Signal Return
148	Video Connector Position 8 - Blue Video Signal Return
149	Video Connector Position 9 - Power Line for DDC
150	Video Connector Position 10 - SYNC Signal Return
151	Video Connector Position 11 - ID Bit 11 (Reserved)
152	Video Connector Position 12 - Data Line for DDC
153	Video Connector Position 13 - Horizontal Sync
154	Video Connector Position 14 - Vertical Sync
155	Clock Line for DDC
161	KB Connector Position 1 - Keyboard Data
162	KB Connector Position 2 - No Connection
163	KB Connector Position 3 - Signal Ground
164	KB Connector Position 4 - +5V Supply
165	KB Connector Position 5 - KB Clock
166	KB Connector Position 6 - No Connection
171	Mouse Connector Position 1 - Mouse Data
172	Mouse Connector Position 2 - No Connection
173	Mouse Connector Position 3 - Signal Ground

	EIA-RS-485 Tx-
462	Connector for Communications Port and Daisy Chain position 7 - EIA-RS-485 Clock-
464	Connector for Communications Port and Daisy Chain position 8 - EIA-RS-485 Clock+
466	Connector for Communications Port and Daisy Chain position 9 - EIA-RS-485 Rx+
468	Connector for Communications Port and Termination position 1 - EIA-RS-485 Tx+
470	Connector for Communications Port and Termination position 2 - EIA-RS-232 TxD
472	Connector for Communications Port and Termination position 3 - EIA-RS-232 RxD
474	Connector for Communications Port and Termination position 4 - EIA-RS-485 Rx-
476	Connector for Communications Port and Termination position 5 - Ground
478	Connector for Communications Port and Termination position 6 - EIA-RS-485 Tx-
480	Connector for Communications Port and Termination position 7 - EIA-RS-485 Clock-
482	Connector for Communications Port and Termination position 8 - EIA-RS-485 Clock+
484	Connector for Communications Port and Termination position 9 - EIA-RS-485 Rx+
486	Connector for Communications Port and Daisy Chain position 1 - EIA-RS-485 Tx+
488	Connector for Communications Port and Daisy Chain position 2 - EIA-RS-232 TxD
490	Connector for Communications Port and Daisy Chain position 3 - EIA-RS-232 RxD
492	Connector for Communications Port and Daisy Chain position 4 - EIA-RS-485 Rx-
494	Connector for Communications Port and Daisy Chain position 5 - Ground

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496 Connector for Communications Port and Daisy Chain position 6 -
EIA-RS-485 Tx-
498 Connector for Communications Port and Daisy Chain position 7 -
EIA-RS-485 Clock-
500 Connector for Communications Port and Daisy Chain position 8 -
EIA-RS-485 Clock+
502 Connector for Communications Port and Daisy Chain position 9 -
EIA-RS-485 Rx+
504 Connector for Communications Port and Termination position 1 -
EIA-RS-485 Tx+
506 Connector for Communications Port and Termination position 2 -
EIA-RS-232 TxD
508 Connector for Communications Port and Termination position 3 -
EIA-RS-232 RxD
510 Connector for Communications Port and Termination position 4 -
EIA-RS-485 Rx-
512 Connector for Communications Port and Termination position 5 -
Ground
514 Connector for Communications Port and Termination position 6 -
EIA-RS-485 Tx-
516 Connector for Communications Port and Termination position 7 -
EIA-RS-485 Clock-
518 Connector for Communications Port and Termination position 8 -
EIA-RS-485 Clock+
520 Connector for Communications Port and Termination position 9 -
EIA-RS-485 Rx+
610 Terminator for Daisy Chain
612 Resistor
614 Resistor
616 Resistor
620 Terminator Position 1
626 Terminator Position 4
630 Terminator Position 6
632 Terminator Position 7
634 Terminator Position 8
636 Terminator Position 9

DETAILED DESCRIPTION OF THE INVENTION

Preferred Embodiment - Figs. 1, 2, 3, and 4

A preferred embodiment of the control and monitoring system of the present invention is illustrated in FIG. 1 (rear view). In the presently preferred embodiment of the control and monitoring system, up to sixteen (16) computer systems may be controlled and monitored from a single control and monitoring system and up to two hundred fifty six (256) if a plurality of control and monitoring systems are connected together. However, those skilled in the art will recognize that the number of possible connections may be modified to accommodate an unlimited number of computer systems.

A main unit housing **8** provides a mounting base for the Mini-DIN, DB9, and fifteen position D-sub connectors. An external video display device compatible with the VGA standard may be connected to an External Video Port **10**. An External keyboard may be connected to an External Keyboard Port **14**. An external mouse or other pointing device may be connected to an External Mouse Port **16**. A computer or communications device capable of communicating with a computer may be connected via a standard IBM-type DB9 serial cable to the Communications Port **12**. A computer system may be connected to any of Keyboard-Video-Mouse (KVM) Ports 1-16 (**20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50**).

Fig. 2 details the present front view of the main unit **8** of the control and monitoring system. Power is supplied to the control and monitoring system through a power connector **62**. Power to a video display **68** (Fig. 4), a keyboard **72**, and a touchpad **74** (Fig. 3) is sent out through a power connector **60**. The video display **68** is connected to an internal video port **54**. The keyboard **72** is connected to an internal keyboard port **56**. The touchpad **74** is connected to an internal mouse port **58**.

Fig. 3 details the present rear view of the control and monitoring system in the open position. A power supply **66** receives power when a power cord is plugged into AC power receptacle **64** and connecting the male end of the three-prong AC power cord into a source for AC power such as a public utility wall outlet or a battery backup system. The

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control and monitoring system receives power from a power supply cable 80 connected to a power connector 60. A first housing 69 houses a display 68. A second housing 70 houses a combined keyboard and pointing device comprising a keyboard 72, and a touchpad 74. The first housing and second housing are rotatably connected such that the display may be stored against the keyboard and pointing device and flipped out when needed. The first housing and second housing so connected are referred to as the administration station. The second housing may have a cowling or cover in a shape complementary to the shape of the power supply 66 and the main unit housing 8 such that any cables running between the administration station and the main unit housing 8 are covered when the administration station is stored. A power cable 84 supplies power from the main unit housing 8 through a power connector 60 to a display 68, a keyboard 72, and a pointing device 74. A keyboard cable 86 connects the internal keyboard port 56 to the keyboard 72. A mouse cable 88 connects the internal mouse port 58 to the touchpad 74. A video cable 90 connects the internal video port 54 to the video display 68. A cable tray arm 82 relieves stress on the cables, organizes the cables neatly and prevents them from tangling. The main unit 8 is connected to the power supply 66 and attached to a rail 92 and a rail 94. The cable tray arm 82 is attached to the rail 94. The keyboard 72, touchpad 74, and display 68 are mounted on a rail 92 and a rail 94 and may slide forward and backward along the rails. The display 68 rotates up and down via two hinges or other rotation mechanism.

Fig. 4 details the present front view of the control and monitoring system in an open position. The control and monitoring system may be mounted in a standard nineteen-inch wide rack but may also be used without the benefit of a rack. The preferred embodiment of the present invention consumes not more than 1U (1.75 inches) of vertical space while the keyboard 72, touchpad 74, and display 68 are in the stored position. Of course, the control and monitoring system may consume more or less vertical space while maintaining a compact profile.

Fig. 5 details a cable used to connect a computer system to any of the KVM Ports 1-16. The fifteen position D-sub connector 102 connects to any of the KVM Ports 1-16 (20,22,24,26,28,30,32,34,36,38,40,

42,44,46,48,50). The fifteen position D-sub connector **104** connects to the graphics adapter of the remote computer. The mini-DIN connector **106** connects to the keyboard port of the remote computer. The mini-DIN connector **108** connects to the mouse port of the remote computer.

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KVM Connector Position 132	Mouse Data	Mouse Connector Position 171
KVM Connector Position 133	Horizontal Sync	Video Connector Position 153
KVM Connector Position 134	Vertical Sync	Video Connector Position 154
KVM Connector Position 135	Keyboard and Mouse Ground	Keyboard Connector Position 163 and Mouse Connector Position 173

Additionally, the cable shield runs along the portion of the KVM cable **100** extending from the Keyboard-Video-Mouse Male fifteen position D-sub Connector **102** side to the Video Male fifteen position D-sub Connector **104** side.

Figs. 7 and 8 depict a block diagram of the control and monitoring system. Two Keyboard-Video-Mouse (KVM) ports (**20,22,24,26,28,30,32,34,36,38,40,42,44,46,48,50**) connect to a processor **232, 234, 236, 238, 240, 242, 244, or 246**. Each of the processors controls two KVM ports. All eight processors **232, 234, 236, 238, 240, 242, 244, and 246** connect to a processor **296**. Processor **296** connects to a video switch **324** and a processor **320**.

Keyboard and mouse signals **200** are sent and received between a KVM port **48** and a processor **232**.

Keyboard and mouse signals **202** are sent and received between a KVM port **50** and a processor **232**.

Keyboard and mouse signals **204** are sent and received between a KVM port **44** and a processor **234**.

Keyboard and mouse signals **206** are sent and received between a KVM port **46** and a processor **234**.

Keyboard and mouse signals **208** are sent and received between a KVM port **40** and a processor **236**.

Keyboard and mouse signals **210** are sent and received between a KVM port **42** and a processor **236**.

Processors 232, 234, 236, 238, 240, 242, 244, and 246 are referred to as Port Controllers.

Keyboard signals 316 travels between a processor 296 and keyboard ports 14 and 56. Mouse signals 318 travel between a processor 296 and mouse ports 16 and 58.

Fig. 8 shows a video switch 324. A processor 296 asserts a video select signal 322 to a video switch 324. Processor 296 is referred to as the Main Controller.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 326 pass from KVM port 20 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 328 pass from KVM port 22 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 330 pass from KVM port 24 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 332 pass from KVM port 26 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 334 pass from KVM port 28 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 336 pass from KVM port 30 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 338 pass from KVM port 32 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 340 pass from KVM port 34 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 342 pass from KVM port 36 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 344 pass from KVM port 38 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 346 pass from KVM port 40 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 348 pass from KVM port 42 to video switch 324.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals 350 pass from KVM port 44 to video switch 324.

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Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals **352** pass from KVM port **46** to video switch **324**.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals **354** pass from KVM port **48** to video switch **324**.

Red, Green, Blue, Vertical Sync, and Horizontal Sync video signals **356** pass from KVM port **50** to video switch **324**.

Control **368** travels between a programmable logic device **364** and a processor **370**. Data **320** travels between a processor **296** and a processor **370**. A clock generator **372** provides a clock signal **374** to a processor **370**. Processor **370** is referred to as the Host Controller.

Transmit Data (TX) signals **384** travels from an EIA-RS-232 port **12** to an EIA-RS-232 Transmitter/Receiver **376**. Receive Data (RX) signals **386** travels from an EIA-RS-232 Transmitter/Receiver **376** to an EIA-RS-232 port **12**. TX data signals **386** travel from an EIA-RS-232 Transmitter/Receiver to a processor **370**. RX data signals **390** travel from a processor **370** to an EIA-RS-232 Transmitter/Receiver **376**.

A single-ended transmit/receive data signal **398** travels between a processor **370** and an EIA-RS-485 transceiver **378**. A differential transmit/receive data high signal **392** travels between the EIA-RS-485 transceiver **378** and the communications port **12**. A differential transmit/receive data low signal **396** travels between the EIA-RS-485 transceiver **378** and the communications port **12**.

A differential receive/transmit data high signal **400** travels between the communications port **12** and an EIA-RS-485 transceiver **380**. A single-ended receive/transmit data signal **406** travels between the EIA-RS-485 transceiver **380** and the processor **370**. A differential receive/transmit data low signal **404** travels between the communications port **12** and the EIA-RS-485 transceiver **380**.

A single-ended clock signal **414** passes between the processor **370** and an EIA-RS-485 transceiver **382**. A differential clock high signal **408** passes between the EIA-RS-485 transceiver **382** and the communications port **12**. A differential clock low signal **412** travels between the communications port **12** and the EIA-RS-485 transceiver **382**. A Horizontal Sync signal **358** passes from a video switch **324** to a programmable logic

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device **364**. A Vertical Sync signal **360** passes from a video switch **324** to a programmable logic device **364**.

Horizontal Sync and Vertical Sync signals **367** pass from a programmable logic device **364** to a Video Driver **420**. On screen menu display data passes over data path **366** from a programmable logic device **364** to a Video Driver **420**.

Red, Green, and Blue video signals **362** pass from a video switch **324** to video driver **420**.

Video driver **420** takes the Red, Green, and Blue video signals **362**, and the Horizontal and Vertical Sync signals **367** and sends Red, Green, Blue, Horizontal Sync, and Vertical Sync signals **422** to video port **10** and Red, Green, Blue, Horizontal Sync, and Vertical Sync signals **424** are sent video port **54**.

Fig. 9 shows a daisy chain cable **440** used to daisy chain multiple control and monitoring systems together. A connector for the communications port and daisy chain **444** and a connector for the communications port and termination **446** comprises one end of the cable. A connector for the communications port and daisy chain **442** and a connector for the communications port and termination **448** comprise the other end of the cable.

Fig. 10 shows a position mapping for each of the connectors of the daisy chain cable **440**. The following tables show the mapping of the positions:

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Position on connector for communications port and daisy chain 444	Description	Position Connection
Position 1 450	EIA-RS-485 Tx+	Connector 446 Position 1 468 and Connector 442 Position 1 486
Position 2 452	EIA-RS-232 TxD	Connector 446 Position 2 470
Position 3 454	EIA-RS-232 RxD	Connector 446 Position 3 472
Position 4 456	EIA-RS-485 Rx-	Connector 446 Position 4 474 and Connector 442 Position 4 492
Position 5 458	Ground	Connector 446 Position 5 476 and Connector 442 Position 5 494
Position 6 460	EIA-RS-485 Tx-	Connector 446 Position 6 478 and Connector 442 Position 6 496
Position 7 462	EIA-RS-485 Clock-	Connector 446 Position 7 480 and Connector 442 Position 7 498
Position 8 464	EIA-RS-485 Clock+	Connector 446 Position 8 482 and Connector 442 Position 8 500
Position 9 466	EIA-RS-485 Rx+	Connector 446 Position 9 484 and Connector 442 Position 9 502

Position on connector for communications port and daisy chain 442	Description	Position Connection
Position 1 486	EIA-RS-485 Tx+	Connector 448 Position 1 504 and Connector 444 Position 1 450
Position 2 488	EIA-RS-232 TxD	Connector 448 Position 2 506
Position 3 490	EIA-RS-232 RxD	Connector 448 Position 3 508
Position 4 492	EIA-RS-485 Rx-	Connector 448 Position 4 510 and Connector 444 Position 4 456
Position 5 494	Ground	Connector 448 Position 5 512 and Connector 444 Position 5 458
Position 6 496	EIA-RS-485 Tx-	Connector 448 Position 6 514 and Connector 444 Position 6 460
Position 7 498	EIA-RS-485 Clock-	Connector 448 Position 7 516 and Connector 444 Position 7 462
Position 8 500	EIA-RS-485 Clock+	Connector 448 Position 8 518 and Connector 444 Position 8 464
Position 9 502	EIA-RS-485 Rx+	Connector 448 Position 9 520 and Connector 444 Position 9 466

Fig. 11 shows a schematic view of a terminator **610** used on the open end of the first and last cables in a daisy chain of multiple control and monitoring systems. A resistor **612** is connected to terminator position 1 **620** and terminator position 6 **630** such that when the terminator **610** is connected to communications port and termination connector **446**, communications port and daisy chain connector **444** position 1 **450** and communications port and daisy chain connector **444** position 6 **460** are terminated. A resistor **614** is connected to terminator position 4 **626** and terminator position 9 **636** such that when terminator **610** is connected to communications port and termination connector **446**, communications port and daisy chain connector **444** position 4 **456** and

communications port and daisy chain connector **444** position 9 **466** are terminated. A resistor **616** is connected to terminator position 7 **632** and terminator position 9 **634** such that when terminator **610** is connected to communications port and termination connector **446**, communications port and daisy chain connector **444** position 7 **462** and communications port and daisy chain connector **444** position 8 **464** are terminated.

Fig. 12A shows a rear view of the terminator and Fig. 12B shows a front view of the terminator. All positions on the front connector of the terminator are connected to each respective position on the rear connector of the terminator in a straight through fashion.

In the preferred embodiment, processors **232, 234, 236, 238, 240, 242, 244, 246, 296, and 370** are Atmel Corporation model AT89S8252 microcontrollers or equivalent; programmable logic devices **298 and 364** are Xilinx Corporation model XC9536 Complex Programmable Logic Devices (CPLDs) or equivalent; flash memory **308** is Atmel Corporation model AT29C020 or equivalent; NVRAM **302** is Dallas Semiconductor model DS1230AB-70 or equivalent; EIA-RS-232 Transmitter/Receiver **376** is Dallas Semiconductor model DS232 or equivalent; EIA-RS-485 Transceiver **378, 380, and 382** are Maxim Integrated Products model MAX485 or equivalent.

A ~~floppy disk~~ ^{Compact disc} comprising object code for the programmable logic and the microcontrollers is attached. ^{The contents of the compact disc should be copied to a hard disk.} The following equipment should be used when programming the programmable logic and the microcontrollers:

- 1) Laptop or PC running Windows (NT, Win95 or Win98) Operating System.
- 2) Equinox Activ8r Programmer connected to the Laptop or PC's serial port via a serial straight-thru EIA-RS-232 DB9 female to DB9 male cable.
- 3) A 10 conductor flat ribbon cable to perform in system programming (ISP).
- 4) Equinox Meridian Suite programming software installed in the laptop or PC.
- 5) Serial straight-thru EIA-RS-232 DB-9 female to DB-9 male cable to interconnect between the control and monitoring system and the Laptop or PC.

- 6) Xilinx Foundation F1.5 software installed in the laptop or PC, to use the JTAG programmer program jtagprog.exe.
- 7) Xilinx Parallel Cable III Model DLC5 that connects to the laptop or PC.

The following procedure should be used in order to program the Programmable Logic, Programmable Logic **298** and **364** should be connected to a 6 pin JTAG connector in order to enable In System Programming from a programming device:

- 1) Make sure the Xilinx Foundation F1.5's JTAG programmer is properly installed in the laptop or PC and that jtagprog.exe is in the execution path. Open an MSDOS Shell.
- 2) Connect the DB-25 end of the Xilinx DLC5 Parallel Cable III to the laptop or PC's parallel port.
- 3) Connect the 6 pin ribbon cable end of the Xilinx DLC5 Parallel Cable III to the Host Controller's Programmable Logic **364** to the 6 pin JTAG connector. Apply power to the control and monitoring system.
- 4) On the laptop or PC in the MSDOS shell, change directory to the floppy diskette source and execute "proghost". Wait for operations of erase, program and verification of the Host Controller's Programmable Logic **364** and finally for the command prompt.
- 5) Power down the control and monitoring system and move the 6 pin ribbon cable end of the Xilinx DLC5 Parallel Cable III from the Host Controller's Programmable Logic **364** JTAG header pins to the Main Controller's Programmable Logic **298** JTAG header pins. Apply power to the control and monitoring system.
- 6) On the laptop or PC in the MSDOS shell, change directory to the floppy diskette source and execute "progmain". Wait for operations of erase, program and verification of the Main Controller's Programmable Logic **298** and finally for the command prompt.

Power down the control and monitoring system and remove the 6 pin ribbon cable end of the Xilinx DLC5 Parallel Cable III from the Main Controller's Programmable Logic **298** JTAG header pins.

The following procedure should be used in order to program the Host Controller, processor **370** should be connected to a 10 pin ISP connector in order to enable In System Programming from a programming device:

- 1) Connect the Activ8r programmer to the Host Controller, processor **370** to the 10 pin ISP connector via the 10 conductor flat ribbon cable. Be sure to jumper the programmer to use its own external power source, instead of the target's. Apply power to the programmer unit and to the control and monitoring system.
- 2) Run Meridian programmer software and initialize the programmer hardware via the serial port for flashing the Host Controller, processor **370**. Load into the buffer the AdmCtrl.hex code from the floppy diskette source. Erase the Host Controller, processor **370** and then program it with the data from the program buffer.
- 3) Power down the control and monitoring system and remove the interconnecting ISP cable.

The following procedure should be used in order to program the Main Controller, processor **296** and Port Controllers, processors **232, 234, 236, 238, 240, 242, 244, and 246**:

- 1) Power up the control and monitoring system. Connect the serial EIA-RS-232 cable between the DB9 serial port **12** and the Laptop or PC's serial port.
- 2) Insert the source diskette to Laptop or PC, run CPDnld and use it to communicate with the Host Controller, processor **370** via the DB9 serial port **12**.
- 3) Login with a predetermined password. The following password could be used: "System Administrator".

- 4) Download to the internal flash EPROM of the Main Controller, processor **296** with the OperDnld.hex code from the floppy diskette source.
 - (a) To the "?" prompt type "Ctrl]" which will invoke the command mode.
 - (b) To the "Cmd:" prompt type "d"
 - (c) To the "Enter filename:" prompt type "a:\OperDnld.hex"
 - (d) To the "Enter destination (D=OperInternal, E=Port, F=OperFlashEPROM or G=OperNVRAM)" prompt type "D".
 - (e) After completion of the download process, to the "Cmd:" prompt type "r" to return to terminal mode.
 - (f) Type Enter key to elicit a "?" prompt from the Administrator software.
- 5) Download to one of the internal flash EPROM of one of the Port Controllers, processors **232, 234, 236, 238, 240, 242, 244, 246** with the PortCtrl.hex code from the floppy diskette source.
 - (a) To the "?" prompt type "Ctrl]" which will invoke the command mode.
 - (b) To the "Cmd:" prompt type "d"
 - (c) To the "Enter filename:" prompt type "a:\PortCtrl.hex"
 - (d) To the "Enter destination (D=OperInternal, E=Port, F=OperFlashEPROM or G=OperNVRAM)" prompt type "E".
 - (e) After completion of the download process, to the "Cmd:" prompt type "r" to return to terminal mode.
 - (f) Type Enter key to elicit a "?" prompt from the Administrator software.
- 6) Download to the Operation processor's external flash EPROM with the OperCtrl.hex code from the floppy diskette source.
 - (a) To the "?" prompt type "I" to switch to internal Operation code memory.
 - (b) To the "?" prompt type "Ctrl]" which will invoke the command mode.
 - (c) To the "Cmd:" prompt type "d"
 - (d) To the "Enter filename:" prompt type "a:\OperCtrl.hex"
 - (e) To the "Enter destination (D=OperInternal, E=Port, F=OperFlashEPROM or G=OperNVRAM)" prompt type "F".

- (f) After completion of the download process, to the "Cmd:" prompt type "r" to return to terminal mode.
- (g) Type Enter key to elicit a "?" prompt from the Administrator software.

7) Download to the Operation processor's NVRAM with the DefNVRAM.hex code from the floppy diskette source.

- (h) To the "?" prompt type "I" to switch to internal Operation code memory.
- (i) To the "?" prompt type "Ctrl]" which will invoke the command mode.
- (j) To the "Cmd:" prompt type "d"
- (k) To the "Enter filename:" prompt type "a:\DefNVRAM.hex"
- (l) To the "Enter destination (D=OperInternal, E=Port, F=OperFlashEPROM or G=OperNVRAM)" prompt type "G".
- (m) After completion of the download process, to the "Cmd:" prompt type "r" to return to terminal mode.
- (n) Type Enter key to elicit a "?" prompt from the Administrator software.

7) Reset the control and monitoring system by powering down and then waiting for a few seconds before powering up and the unit should be ready to operate for its designed function.

Each computer to be controlled and monitored is connected to the control and monitoring system via a Keyboard-Video-Mouse (KVM) Cable **100**. A keyboard connector **106** plugs into the keyboard port of the computer to be controlled and monitored. A mouse connector **108** plugs into the mouse port of the computer to be controlled and monitored. A video connector **104** plugs into the video port of the computer to be controlled and monitored. A KVM connector **102** plugs into one of the KVM ports **20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50**.

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attached to the communications port **12** via a modem cable or via a null modem cable and a modem. The processor **370**, also known as the Host Controller, also looks for EIA-RS-232 Receive Data signals **386** coming from the EIA-RS-232 Transmitter/Receiver **376** and passes the Receive Data signal **390** to the processor **370**. The processor **370** can send acknowledgements or other data via EIA-RS-232 Transmit Data signal **386** to the EIA-RS-232 Transmitter/Receiver **376** which then passes EIA-RS-232 Transmit Data signals **384**.

The computer attached to communications port **12** may transmit any of several commands, including but not limited to:

- Print the available commands menu
- Login and establish an administration (admin) session
- Logout from admin session
- Reset the entire system
- Read current configuration settings
- Set configuration settings
- Switch operating software between internal flash memory on the processor **296** and flash memory **308**.
- Perform diagnostic tests
- Set local options
 - Select the Port Controllers that will be active in subsequent operations of erase, program, and upload.
- Switch the execution of processor **296** (also known as the Main Controller) between internal flash memory and flash memory **308**
- Erase internal flash memory on the processor **296**, flash memory **308**, or any or all of the Port Controllers' flash memory.
- Download code and data and program internal flash memory on the processor **292**, flash memory **308**, or for any or all of the Port Controllers' flash memory.
- Download code and data to NVRAM **302**
- Upload code and data from flash memory of processor **292**, flash memory **308**, or any or all of the Port Controllers' flash memory.
- Upload code and data from NVRAM **302**
- Turn LCD +12V power on and off

- Turn Debug LED on and off
- Send commands and/or data to processor **296** (also known as the Main Controller)
- Get status and/or data from processor **296** (also known as the Main Controller)
- Submit any of the above to another control and monitoring system connected to communications port **12** via at least one daisy chain cable **440**.

Once the Host Controller receives one of the above commands it processes it and looks for more commands from the remote computer communicating through the communications port **12**.

Red, Green, Blue, Horizontal Sync, and Vertical Sync (RGBHV) Signals **326, 328, 330, 332, 334, 336, 338, 340, 342, 344, 346, 348, 350, 352, 354, 356** are received by the video switch **324**. A video select signal **322** causes the video switch **324** to pass Red, Green, and Blue video signals **362** to a video driver **420**. The video select signal **322** also causes the video switch **324** to pass Horizontal and Vertical Sync signals to a Programmable Logic **364**.

The processor **370**, also known as the Host Controller, takes the local Horizontal Sync generated by Programmable Logic **364**, generates the local Vertical Sync and passes to the Programmable Logic **364**. The processor **296**, also known as the Main Controller passes data over the data path **366** for on screen menu display to the video driver **420**. Red, Green, and Blue video signals are overlaid with on screen menu display data, if any, and a set of amplified Red, Green, Blue, Horizontal Sync, and Vertical Sync video signals **422** are sent to video port **10**. A set of amplified Red, Green, Blue, Horizontal Sync, and Vertical Sync video signals **424** are sent to video port **54**.

The processor **296**, also known as the Main Controller also checks to see if Vertical Sync signal **358** and Horizontal Sync signal **360** are being provided by one of the remote computers through the video switch **324**. If there are no such signals, the Main Controller enables the local Vertical Sync and Horizontal Sync signals and passes Horizontal Sync and

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- As keyboard signals **316** and mouse signals **318** are received into processor **296**, the Main Controller detects such a condition and does the following:
 - Reads the keyboard and mouse data
 - Checks to see if the menu entry key has been typed. The menu entry key is a predetermined character sequence. For example, either the "Print Screen" or "Pause" keys could be used to trigger the on screen menu. Other keys to invoke the on screen menu may also be designated by a human user.
 - If the menu entry key has not been typed, the keyboard and mouse data is passed to the currently selected KVM port through the appropriate Port Controller.
 - If the menu entry key has been typed, the Main Controller performs the following:
 - Set currently selected port to DESELECTED to Port Controller
 - Present a Main menu on screen
 - Process the Main menu commands in the following manner until an exit or cancel command or a timeout is received:
 - Present the selected port number on screen
 - Look for a menu command
 - If an Exit command or a timeout is received then
 - Re-initialize the keyboard **72** and the touchpad **70** to the currently selected port states. For example, the state of the mouse scaling and resolution.
 - Re-initialize any keyboard attached to keyboard port **14** to the currently selected port states. For example, the state of "Num Lock" or "Caps Lock".
 - Re-initialize any pointing device attached to mouse port **16** to the currently selected port states.
 - Remove the menu from the screen and show the currently selected port's video.
 - If a Set Selected Port command is received then the user is allowed to select a port using the number keys, function keys, or cursor keys on the keyboard and then confirm the selection with the Enter key on the keyboard. The state of the selected port is set to SELECTED and it

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- If a Discard Setup command is received then return to the Main menu without saving any changes.
- If an Edit Ports 1-8 command is received then display information about KVM ports **20, 22, 24, 26, 28, 30, 32, and 34** and allow the user to type in a system name and description associated with the port using the arrow keys and character keys. If a Previous command is selected with the arrow keys or page up key then return to the Setup menu. If an Exit command is selected process it as described above.
- If an Edit Ports F1-F8 command is received then display information about KVM ports **36, 38, 40, 42, 44, 46, 48, and 50** and allow the user to type in a system name and description associated with the port using the arrow keys and character keys. If a Previous command is selected with the arrow keys or page up key then return to the Setup menu. If an Exit command is selected process it as described above.
- If a Save Setup command is received then request the user to enter the password. If the password matches the currently saved password then update and save the settings to flash memory **308** and return to Main menu. If the password does not match then return to the Setup menu.
- If a Change Password command is received then request the user to enter the currently saved password. If the password does not match then return to the Setup menu. If the password matches the saved password then allow the user to enter a new password twice. If the two new passwords match then save it to flash memory **308** and return to the Main menu. If the two new passwords do not match then repeat the Change Password process.
- Polls the Port Controller for the selected port for new changes in keyboard and mouse states and status.

- If new keyboard states and status are available from the KVM port they are sent to the keyboard **72** and the external keyboard port **14**.
- If new mouse states and status are available from the KVM port they are sent to the touchpad **70** and the external mouse port **16**.
- If no keyboard or mouse "connected" signals are detected from the KVM port for a specified period of time then the Port Controller will mark the port INACTIVE and return such status. Poll the Port Controller for ports marked as ACTIVE ports
 - If new states and status are available then update the states of the port and mark it as ACTIVE
 - If no keyboard or mouse "connected" signals are detected from the KVM port for a specified period of time then that port is marked INACTIVE
- Poll the Port Controller for ports marked as INACTIVE ports
 - If keyboard or mouse "connected" signals are detected from the KVM port for a specified period of time then mark the status for the port as ACTIVE
 - If no keyboard or mouse "connected" signals are detected from the KVM port for a specified period of time then keep the status for the port as INACTIVE

Any of the eight processors 232, 234, 236, 238, 240, 242, 244, 246 are also known as a Port Controller.

Each Port Controller sends and receives keyboard and mouse data between the Main Controller and each of two KVM ports. Each Port Controller performs the following tasks in a loop:

- Check for keyboard or mouse data from the Main Controller
- If the keyboard or mouse data is for one of the two KVM ports connected to the Port Controller then send the keyboard and mouse data through the appropriate KVM port.
- Check for a request for status from the Main Controller
- If a request for status from the Main Controller is received then send the keyboard or mouse states and the status of either ACTIVE or INACTIVE for the KVM port to the Main Controller.
- Check for keyboard or mouse data from the KVM ports

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- If there is keyboard or mouse data from the KVM ports then process it, save the state such as Num Lock, Caps Lock and send the appropriate responses back through the KVM ports. Such states are sent back to the keyboard or mouse on the next poll from the Main Controller.
- Poll to see if there is a computer that is asserting the keyboard and mouse "connected" signals going to each of the two KVM ports. If there is a connection within a specified period of time then mark the port as ACTIVE. If there is no connection within a specified period of time then mark the port as INACTIVE.

Multiple control and monitoring systems may be daisy chained together. The first control and monitoring system is designated as a Master System. Each additional control and monitoring system is referred to as a Slave System. A connector for communications port and daisy chain **444** of a daisy chain cable **440** plugs into the communications port **12** of the Master System. A connector for communications port and daisy chain **442** plugs into the communications port **12** of a Slave System. Additional slave systems are added by connecting a connector for communications port and daisy chain **444** of an additional daisy chain cable **440** into the connector for communications port and termination **448** of a Slave System at the end of the daisy chain and plugging the connector for communications port and daisy chain **442** of the communications cable **440** into the communications port **12** of the Slave System to be added. The first and last daisy chain cable in the daisy chain requires a terminator **610** on the communications port and termination connector **446** or **448**. A KVM Cable **100** also connects each Slave System to the Master System. The keyboard connector **106** is plugged into the external keyboard port **14** of a Slave System. The mouse connector **108** is plugged into the external mouse port **16** of the Slave System. The video connector **104** is plugged into the external video port **10** of the Slave System. The KVM connector **102** plugs into one of the KVM ports **20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50** of the Master System.

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The Master System and Slave Systems communicate over the daisy chain cables **440** using the Serial Peripheral Interface (SPI) protocol as documented in "Microcontroller Data Book, AT86 Series" published December 1997 by Atmel Corporation. The MOSI signal called out in the data book is seen here as an RS-485 Tx signal pair (Tx+, Tx-). The MISO signal called out in the data book are seen here as the RS-485 Rx signal pair (Rx+, Rx-). The SCK signal called out in the data book is seen here as the RS-485 Clock signal pair (Clock+, Clock-).

The Master System uses the single-ended Transmit/Receive Data signal **398** to transmit data via EIA-RS-485 Transceiver **378**. The EIA-RS-485 Transceiver **378** transmits data to Slave Systems using the Differential Transmit/Receive Data High signal **392** and the Differential Transmit/Receive Data Low signal **396**.

A Slave System uses the single-ended Transmit/Receive Data signal **398** to receive data via EIA-RS-485 Transceiver **378**. The EIA-RS-485 Transceiver **378** receives data from the Master System using the Differential Transmit/Receive Data High signal **392** and the Differential Transmit/Receive Data Low signal **396**.

The Master System uses the single-ended Receive/Transmit Data signal **406** to receive data via EIA-RS-485 Transceiver **380**. The EIA-RS-485 Transceiver **380** receives data from Slave Systems using the Differential Receive/Transmit Data High signal **400** and the Differential Receive/Transmit Data Low signal **404**.

A Slave System uses the single-ended Receive/Transmit Data signal **406** to transmit data via EIA-RS-485 Transceiver **380**. The EIA-RS-485 Transceiver **380** transmits data to the Master System using the Differential Receive/Transmit Data High signal **400** and the Differential Receive/Transmit Data Low signal **404**.

The Master System uses the single-ended Clock signal **414** to transmit a clock signal to an EIA-RS-485 Transceiver **382**. The EIA-RS-485 Transceiver **382** transmits a differential clock signal to a Slave System using the Differential Clock High signal **408** and the Differential Clock Low signal **412**.

A Slave System receives a single-ended clock signal from the EIA-RS-485 Transceiver **382** through the Clock signal **414**. The EIA-RS-485

Transceiver 382 receives a differential clock signal from the Master System through the Differential Clock High signal 408 and the Differential Clock Low signal 412.

The Master System and Slave Systems communicate with each other through cascade signals using the SPI protocol. The Master System is always in control and through one of its KVM ports 20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50 it can display the video from a Slave System port 10 and control the keyboard port 14 and mouse port 16 of the Slave System. Switching KVM ports in the Master System is equivalent to switching groups of computers, each group of computers being attached to a Slave System. The control menu in the Master System allows the switching and selection of one of the KVM ports 20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50, each of which could represent KVM ports 20, 22, 24, 26, 28, 30, 32, 34, 36, 38, 40, 42, 44, 46, 48, 50 on a Slave System or a combination of groups of computers and individual computers. Once a group is selected the Master System can use cascade signals to command the group associated with the Slave System to display its port selection and allow a specific KVM port on the Slave System to be connected. The process described saves an additional step of having to first select a KVM port on the Master System and then select a KVM port on the Slave System. The use of cascade signals also provides a way to transfer configuration and operational state information from Slave Systems to the Master System for improved user interface and quick access to each KVM port's status information. Thus, the combination of Master Systems and Slave Systems appear to function as one large control and monitoring system.

Additional Embodiments

An additional embodiment is one where the control and monitoring system may be mounted vertically on the side of a rack instead of being mounted horizontally in the rear of a rack.

Another embodiment utilizes the keyboard-video-mouse switch and a plurality of keyboard-video-mouse cables without the keyboard, pointing device, and video display. Such an embodiment would allow connection to other keyboard-video-mouse switches in a tiered fashion whereby a video

display output port of a first keyboard-video-mouse switch is connected to a video display input port of a second keyboard-video-mouse switch, a keyboard input port of the first keyboard-video-mouse switch is connected to a keyboard output port of the second keyboard-video-mouse switch, and a mouse input port of the first keyboard-video-mouse switch is connected to a mouse output port of the second keyboard-video-mouse switch. In addition the cascade signals between the Systems would improve the user interface of the controlling Master system with the video display, keyboard and mouse devices.

Alternative Embodiments

An alternative embodiment comprises processor equivalents such as Central Processing Units (CPUs) instead of processors.

There are various possibilities with regard to the pointing device and video display. The pointing device could be a trackball, graphics tablet, joystick, or mouse. The video display and pointing device could be combined into a touchscreen device.

Another alternative embodiment comprises a KVM switch capable of being daisy chained such that a plurality of interconnected KVM switches appears to be a single switch with more ports than a single KVM switch to a human user.

Advantages

From the description above, a number of advantages of the control and monitoring system become evident:

Rack space required for video display, character input, and pointing device is kept to a minimum.

The number of separate connectors required to connect a system to a KVM switch is reduced from three (3) to one (1), reducing the likelihood of a failure due to a loose connection caused by stress on an individual cable.

The video display, character input device, and pointing device of the control and monitoring system may extend out of a rack as a single unit. Traditional solutions to control and monitor multiple computer

connector on one end and connectors for video display, character input,
and pointing input on the other end.

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CONCLUSION, RAMIFICATIONS, AND SCOPE OF INVENTION

Accordingly, the reader will see that the control and monitoring system of this invention allows a user to apply input to and view the video display output of multiple computer systems. Loss of data is prevented by utilizing multiple processors to handle keyboard and mouse signals and to pass video signals through a video switch. The control and monitoring system may be restarted by a remote operator or have its programming downloaded or uploaded to a remote computer system, easing the job of troubleshooting and maintenance of upgrades. The control and monitoring system consumes a minimum of space by removing the need for separate mini-DIN connectors for keyboard and mouse signals on the control and monitoring system side and using a single fifteen position D-sub connection for keyboard, mouse, and video display signals. Furthermore, the control and monitoring system has the additional advantages of:

- (a) allowing more than the eight (8) systems currently allowed by current keyboard-video-mouse (KVM) switches while consuming the same amount of vertical rack space as a conventional KVM switch;
- (b) providing a video display, a character input device, and a pointing device which consumes a minimum of vertical rack space;
- (c) allowing connection to other control and monitoring systems in a tiered fashion so more than sixteen (16) systems may be controlled and monitored.

Although the description above contains many specificities, these should not be construed as limiting the scope of the invention but as merely providing illustrations of some of the presently preferred embodiments of this invention. For example, the control and monitoring system can use more processors; more than sixteen (16) ports could be used; a different pointing device could be used, etc. Thus the scope of the invention should be determined by the appended claims and their legal equivalents, rather than by the examples given.

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